NT6600 DCG



High-Precision, High-Efficiency Integrated Mill Turn Center

NT6600 DCG



Largest Y-axis Travel in its Class Ultimate Integrated Mill Turn Center Capable of Handling Long and Large-diameter Workpieces

The "NT series" of the ultimate integrated mill turn centers achieves machining capabilities superior to those of machining centers and lathes by gathering DMG MORI SEIKI original and cutting-edge technologies.

Featuring the largest Y-axis travel in its class, the NT6600 DCG is capable of handling long and large-diameter workpieces. The machine ensures the highest productivity ever achieved by thoroughly pursuing improvement of productivity in a fundamental cutting process.



Features of machine

Max. workpiece size

Max. turning length

NT6600 DCG/3000: 3,076 mm (121.1 in.) **NT6600** DCG/4000: 4,076 mm (160.4 in.) **NT6600** DCG/6000: 6,076 mm (239.2 in.)

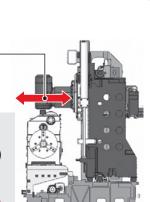
Y-axis travel

660 mm (26.0 in.)

■ Rapid traverse rate

 $\begin{array}{l} \hbox{X-axis 40 m/min (131.2 fpm)} \\ \hbox{Y-axis 30 m/min (98.4 fpm)} \end{array}$

Z-axis 32 m/min (105.0 fpm)



Max. turning diameter $\phi 1,070 \text{ mm } (\phi 42.1 \text{ in.})$

■ Max. workpiece mass (Both-end chucking)

B-type 3,500 kg (7,700 lb.) C-type 7,000 kg (15,400 lb.)

Steady rest

OP

Number of steady rests

NT6600 DCG/6000 NT6600 DCG/3000, 4000 Up to 3 Up to 2

■ Steady rest setup time

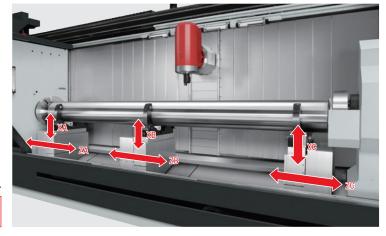
Other company's machine NT6600 DCG

30 min. or more ▶ 5 min. or less

X-axis travel

60~mm (2.4 in.) $_{<25~\text{mm}}$ (1.0 in.): SLU-6Z, K6.1 specifications>

Servo motors are equipped as standard on the X and Z axes, dramatically reducing setup time

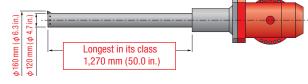


Long boring bar

OP

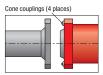
Separate consultation is required when the specification for machining with a long boring bar on the Spindle 2 side is selected





Tool-tip ATC specifications



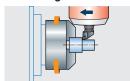


Uses a cone coupling clamping system

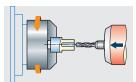
Long boring bar with a diameter of 120 mm (4.7 in.) cannot be arranged by customers.
 Please consult with our sales representative for details.

Machining variations

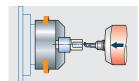
■ Turning



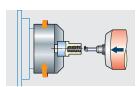




Drilling

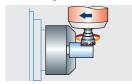


I.D. cutting

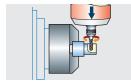


I.D. threading

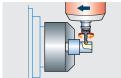
■ Milling



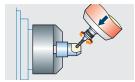
0.D. milling



0.D. hole machining

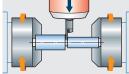


Ball-end milling

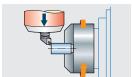


Angular machining

Spindle 2



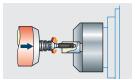
Cut-off



Face cutting



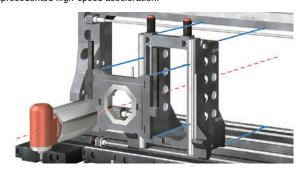
Angular machining



End face hole machining and tapping

Box-in-Box Construction

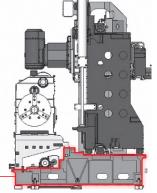
The Box-in-Box Construction supports the saddle at both ends, guiding the axes at the centers of gravity, creating a balanced environment for unprecedented high-speed acceleration.



Flat bed design

A flat bed evenly disperses and absorbs reaction forces during machining, without any distortion. The advantage of this is that the rigidity of Spindle 1 has been greatly improved.

Flat bed design

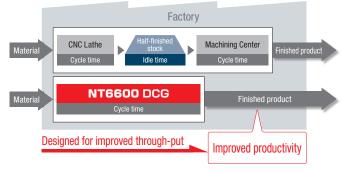


Process integration with a multi-axis machine

It can do various types of machining on one machine, reducing the number of unfinished products and eliminating downtime during transfer of workpieces between machines. The machining flow (through-put) from material to finished product has been improved, and productivity is dramatically increased.

Benefits of process integration

- Eliminates waiting time between processes
- Reduction in half-finished stock
- Reduction in fixture manufacturing costs
- Reduces setup time
- Shortens lead time With no setup changes, machining accuracy is maintained
- Reduces fixture manufacturing costs



Original technology/Mechanism

Driven at the Center of Gravity



Our DCG technology controls vibration, which is one of the main enemies of high speed and high precision, by driving structural parts at their center of gravity.

Max. acceleration

X-axis 0.23 G {2.3 m/s² (7.5 ft/s²)}

Y-axis $0.40 \text{ G} \{3.9 \text{ m/s}^2 (12.8 \text{ ft/s}^2)\}$

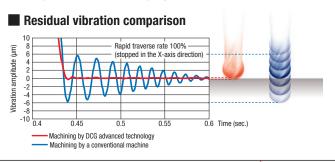
Z-axis 0.18 G {1.8 m/s² (5.9 ft/s²)}

■ Effects of DCG

- ·Improved surface quality
- Outstanding acceleration
- ·Improved roundness

Vibration Control

DCG quickly eliminates vibration after a sudden stop. Machining with conventional machines, on the other hand, produces vibration for a sustained period of time. Rotational vibration, occurring at all acceleration start points, is reduced to an amount proportionate to the distance between the drive point and the center of gravity. The reduction prevents deterioration in the quality of the machined surface.



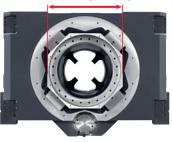
DCG: Driven at the Center of Gravity

Octagonal Ram Construction



The 4 guideways are located diagonally from each other, so they distort symmetrically in response to the heat generated by high-speed travel. This means that the center stays in the same position, offering high-speed. high-precision feed.





Thermal displacement Heat generation The center stays the same

ORC: Octagonal Ram Construction

Tool spindle

Uses a DDS (Direct Drive Spindle) motor which turns the spindle directly. A spindle motor placed inside the spindle headstock enables the spindle to be smaller/lighter, and to offer high output while controlling vibration.



Max. tool spindle speed

8,000 min⁻¹

■ Tool spindle acceleration time

1.8 sec. $(0\rightarrow 8,000 \text{ min}^{-1})$

■ Tool spindle deceleration time

2.6 sec. $(8,000 \rightarrow 0 \text{ min}^{-1})$

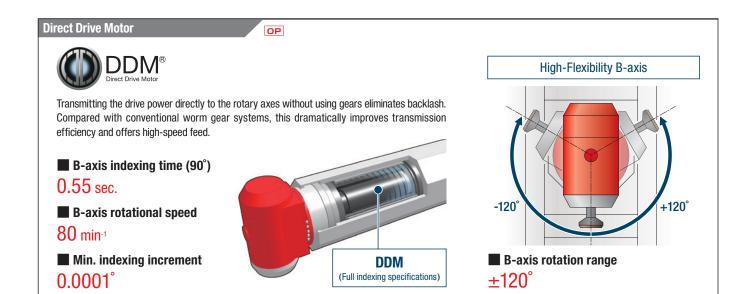
■ Tool-clamping force

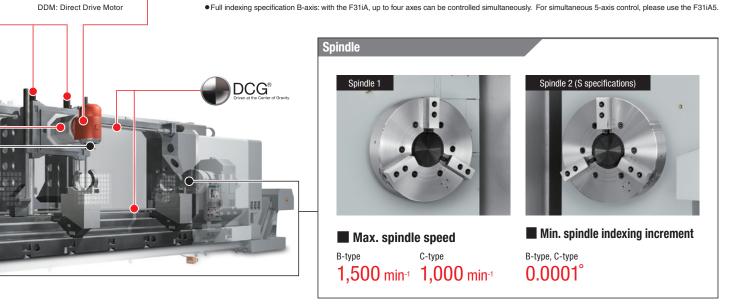
44,000 N (9,891.1 lbf)

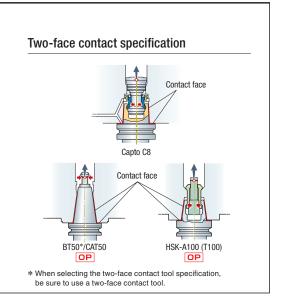
Spindle lubrication

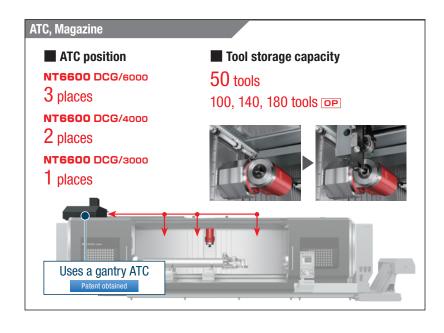
An oil-air lubrication method is used for spindle lubrication. As well as minimizing the amount of lubricant used for reducing the resistance to stirring, this prevents dust infiltration by using the air purge. Also, the oil jacket cooling system controls thermal displacement.



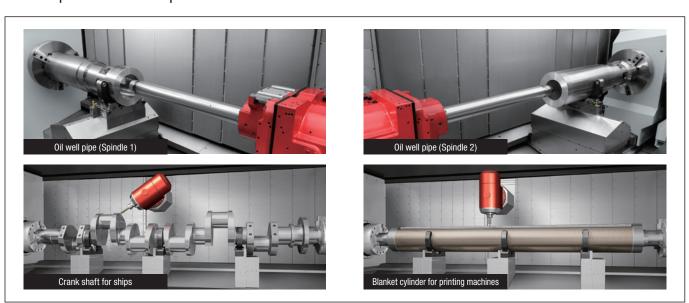








Workpiece samples



Separate consultation is required when the specification for machining with a long boring bar on the Spindle 2 side is selected.

Variations

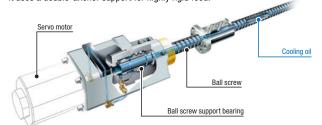
Machine type	Z-axis travel	Number of steady rests	type	Tailstock/Spindle 2	Tailstock
NT6600 DCG /3000	Tool spindle 3,150 mm (124.0 in.)	without/1/2	B-type C-type	/ S	Max. spindle speed B-type: 1,500 min ⁻¹ C-type: 1,000 min ⁻¹
NT6600 DCG /4000	Tool spindle 4,150 mm (163.4 in.)	without/1/2	B-type C-type	/ S	S Spindle 2
NT6600 DCG /6000	Tool spindle 6,150 mm (242.1 in.)	2/3	B-type C-type	/ S	Max. spindle speed B-type: 1,500 min ⁻¹ C-type: 1,000 min ⁻¹



High-precision equipment

Ball screw core cooling

As well as ball screw core cooling, it uses a double-anchor support for highly rigid feed.



Direct scale feedback

OP

A magnetic-type absolute positioning scale is used for the X and Y axes, and an electromagnetic induction type for Z-axis. This offers outstanding positioning accuracy.

■ Resolution 0.1 µm

Tool spindle cooling

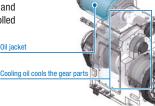
The oil jacket placed around the spindle unit suppresses temperature increases in the tool spindle.

Oil jacket



Tool spindle cooling

Heat generated by the Spindle 1 and Spindle 2 is released, and thermal displacement is controlled by the oil jacket.



Coolant cooling system (separate type)

OP

The temperature of the coolant rises because of heat generated during machining. Circulating the coolant also raises the temperature. This increase has a big effect on the themal displacement of the machine and the dimensional accuracy of the workpiece. We have prepared this unit to control temperature increases in the coolant. Please choose this option when using oil-based coolant, as it can get extremely hot even with a standard coolant pump.

When using oil-based coolant, please be sure to consult with our sales representative.

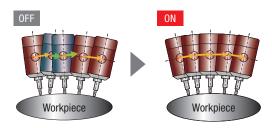
We cannot guarantee that this unit will completely control the coolant temperature. It is designed to help prevent oil temperature increases.



SVC function (Standard features for F31iA5)

The SVC function, in which the program commands for tool tip control are read in advance and compensation is automatically applied to achieve smooth tool feed, is equipped as standard. By combining this function with DDM (Direct Drive Motor), the machine offers greatly improved surface quality and reduced cycle time during 5-axis machining.

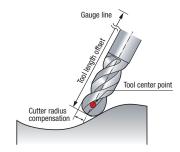
| Motion of the SVC function



The SVC function includes the following functions:

- Al contour control II Nano smoothing II Smooth TC
- Machining mode selection
 G332 tolerance command

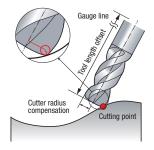
Tool center point control/Cutting point command (Standard features for F31iA5)



Tool center point control

Main features

- The tool path can be controlled from the tool center point.
- No reprogramming is needed when the tool length and the tool diameter are changed.
- NC automatically calculates cutter radius compensation and tool length offsets based on the program commands for tool tip control.



Cutting point command

Main features

- The tool path can be controlled from the cutting point.
- By using cutting point commands, machining using radius end mills or square end mills can be performed without reprogramming when tool length, cutter radius or tool tip corner R are changed.

Improved workability, Maintenance

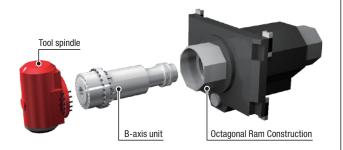
Movable + Swivel-type operation panel

The operation panel moves from side to side, so that it is always close to the operator during setup.



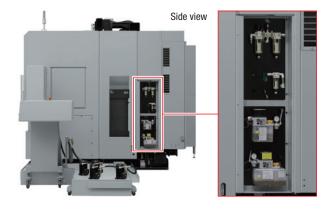
B-axis unitization

Using a unit type B-axis allows easy removal as well as separate replacement of the B-axis unit.



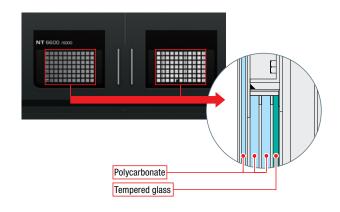
Daily maintenance & inspection

Devices which require frequent inspection are placed together, and the lubricating oil supply port is located at the bottom of the machine for easier oil supply.



Highest level of safety in the world

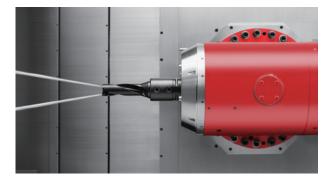
We have used a multi-layered lattice window and PC panel to ensure the world's highest level of operator safety.



Chip disposal

Through-spindle coolant system

Coolant is supplied to the tool tip via a path passing through the middle of the Tool spindle and tool.



Z-axis protector

By using a vertical Z-axis protector, chips fall straight down into the chip conveyor.





Peripheral equipment

External chip conveyor

Two types of chip conveyor have been made available for selection based upon chip shape and material. Please choose one suited to the type of machining you conduct.

	Workpiece material and chip size ○: Suitable ×: Not suitable							
Specifications		Steel		Cast iron	Aluminu	m, non-ferro	us metal	
	Long	Short	Powdery	Short	Long	Short	Powdery	
Hinge type + Scraper type + Drum filter	0	0	0	0	0	0	0	
Hinge type	0	×	×	×	0	×	×	



Short: chips 50 mm (2.0 in.) or less in length, bundles of chips ϕ 40 mm (ϕ 1.6 in.) or less

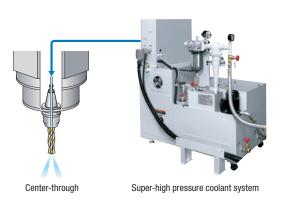
Long: bigger than the above

- The chip conveyor is right disposal only.
- The options table below the general options when using coolant.

 Changes may be necessary if you are not using coolant, or depending on the amount of coolant, compatibility with machines, or the specifications required.
- Please select a chip conveyor to suit the shape of your chips. When using special or difficult-to-cut material (chip hardness HRC45 or higher), please consult with our sales representative.
 We have prepared several options for different chip shapes and material. For details, please consult with our sales representative.

Through-spindle coolant system (super-high pressure coolant system)

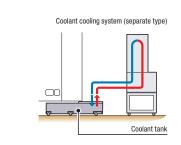
The through-spindle coolant system supplies coolant to the tool tip through the through-hole of the tool spindle and tool. It is effective in eliminating chips, cooling the machining point and lengthening the lives of your tools.



Rated pressure: 3.5 MPa (507.5 psi), 7.0 MPa (1,015 psi)

Recommended equipment Coolant cooling system (separate type)

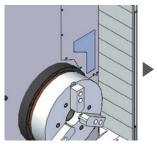
The super-high pressure coolant unit generates a lot of heat because it discharges coolant at high pressure. The coolant cooling unit controls the temperature of the coolant and suppresses temperature increases in the workpiece, tools and table, ensuring stable machining accuracy. This is essential equipment when using super-high pressure coolant. A unit with a heater will be customized.

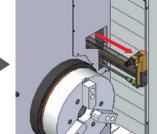




Automatic in-machine tool presetter (tool spindle)

Allows highly efficient tool measurement and easer setups.





B-axis full indexing specification

Minimum indexing increment of 0.0001° offers high-precision machining.

Min. indexing increment

 0.0001°



MAPPS IV

A New High-Performance Operating System for Integrated Mill Turn Centers



19-inch operation panel

A new high-performance operating system that pursues ease of use, and combines the best hardware in the industry with the advanced application/network systems.

- Outstanding operability thanks to upgraded hardware
- Enhanced functionality by using CAM software
- New functions for easier setup and maintenance
- Various types of monitoring, including internal monitoring, are possible on the screen (option)
- ▶ In the event of trouble, DMG MORI SEIKI's remote maintenance service solves it smoothly MORI-NET Global Edition Advance OP

Outstanding operability

Vertical soft-keys

Vertical soft-keys are arranged on the left and right sides of the screen. The vertical soft-keys can be used as option buttons or shortcut keys to which you can assign your desired screens and functions, allowing you to quickly display the screen you want.

Kevhoard

A PC-type keyboard is used as standard, making key input easy. A keyboard with a conventional key layout is also available as an



Functions for multi-axis machining

3D interference checking function

Interference between items such as the spindle, workpiece, soft jaw, tool, holder and turret can be checked in 3D. If interference is detected, the machine will stop operation regardless of whether it is in the automatic or manual mode, providing the highest level of protection against interference.



Interference detected Machine stops automatically

Collisions can be avoided not only during program operation but also during setup

- The 3D interference checking function will check for interference accurately as long as the 3D model exactly matches the actual configuration of the spindles, workpieces, soft iaws, tools, holders and turrets,
- Customized design is required for special shape. For details, please refer to the description of "3D interference checking function" in the NC control unit specifications.
- A cutting simulation that shows how material is removed as machining proceeds cannot be carried out during a 3D interference check.

Improved ease of setup and maintenance

MAPPS IV is packed with new functions for easier setup and maintenance, including the File Display and Memo function that displays operating instructions and manuals on the screen and the Alarm help function that provides instructions when alarms occur.

File display and Memo function



Alarm help function



Faster creation of programs

CAM software DESPRIT

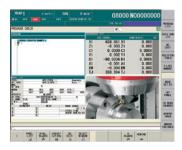
ESPRIT® allows you to create complex 3D programming with high-added value. By just installing the software on your PC with connection to LAN, you will be able to use it. (Once the software is started on the computer, it can be used for up to 7 days without LAN connection.)

- Postprocessor as standard
- CAM software will be ready to use once your machine is installed
- Cost for introducing CAM software can be saved
- ESPRIT® data can be modified on the machine (through Remote Desktop connection*)
- The software can be installed on multiple PCs on the network (It cannot be simultaneously started up on more than one PC)
- 2-year warranty support (including free update)
- * Applicable Operating Systems: Windows Vista Business/Ultimate, Windows 7 Professional/Ultimate
- · A PC is required to use ESPRIT[®]. Please prepare PCs by yourself.

Improved work efficiency

Fixed-point in-machine camera OP Consultation is required

Images taken by cameras installed inside/outside the machine can be viewed on the programming screen. This function is useful for maintenance.



Examples of camera locations

- · Inside machine (to check machining)
- · Tool magazine
- Chip bucket (to check chip accumulation)

Machine specifications

Max. swing of workpiece		Item					DCG/3000		
Capital Capi		May owing of worknings		mm (in)	В	BS 1.070	C (42.1)	CS	
Max. distance between contents									
Mate March March					2 620 (142 5)			2 510 (120 1)	
Max. Luming length	Capacity				3,020 (142.3)			3,310 (136.1)	
Segue									
					164 (6.4)		,	•1	
Part from Class grants		· · ·			104 (0.4)			· I	
Paralle Fame Paralle Paralle									
Part		· · · · · · · · · · · · · · · · · · ·							
Table				11111 (111.)			· · · · · · · · · · · · · · · · · · ·		
Paulis tisseef (Tablicists) - Silvedy rest>	Travel			mm (in.)	-	2,500 (98.4) <without> 2,440 (96.1) <1></without>	-	2,440 (96.1) <1>	
A		Z-axis travel (Tailstock) <steady re<="" td=""><td>est></td><td>mm (in.)</td><td></td><td>-</td><td></td><td>-</td></steady>	est>	mm (in.)		-		-	
Mark spirate speed		XA, XB, XC-axis <steady rest=""></steady>		mm (in.)		60/25 (2.4/1.0) <slu-< td=""><td>6Z, K6.1 specifications></td><td></td></slu-<>	6Z, K6.1 specifications>		
Number of priorite speed ranges 1		ZA, ZB, ZC-axis <steady rest=""></steady>		mm (in.)		2,440 (96.1) <1>	1,870 (73.6) <2>		
		Max. spindle speed		min-1	1,5	500	1,1	000	
Name		Number of spindle speed ranges				2 (winding char	nge-over speed)		
Mile Symbol bearing inversement		Type of spindle nose			JIS A	A ₂ -15	JIS	A ₁ -20	
Min. spands inclaims proterment	Cnindle 4	Through-spindle hole diameter		mm (in.)	185	(7.3)	275	(10.8)	
Spindle forque	Spinale 1	Min. spindle indexing increment				0.00	001°		
Mat. Indicate High speed N = (Pur) 1,4471,061 (1,0672/782 8) <2595(Dental		Spindle bearing inner diameter		mm (in.)	260	(10.2)	360	(14.2)	
Max. sprinke speed Ne of ten) 1.447/USS 1.052782.6 2599(b) conts 1.500		On the Handson	Low speed	N·m (ft·lbf)	3,254/2,386 (2,400.0/1	1,759.8) <25%ED/cont>	6,784/5,574 (5,003.6/	4,111.2) <30 min/cont>	
Max. spindle speed transps		Spindle torque	High speed	N·m (ft·lbf)	1,447/1,061 (1,067.2/	782.6) <25%ED/cont>	3,016/2,481 (2,224.5/	1,830.0) <30 min/cont>	
Spindle 2		Max. spindle speed		min-1					
Sprinde Figure of sportide mose min min min		Number of spindle speed ranges			-	2 (winding change-over speed)	-	2 (winding change-over speed)	
Mine		Type of spindle nose			_		_		
Spindle bearing inner diameter mm (in.)		Through-spindle hole diameter		mm (in.)	_	185 (7.3)	_	275 (10.8)	
		Min. spindle indexing increment			-	0.0001°	_	0.0001°	
	Spindle 2			mm (in.)	-	260 (10.2)	-	360 (14.2)	
Number of tool stations Number of tool s			Low speed		-	3,254/2,386 (2,400.0/1,759.8)	_	6,784/5,574 (5,003.6/4,111.2)	
B_axis indexing time		Spindle torque	High speed	N·m (ft·lbf)	-		-	3,016/2,481 (2,224.5/1,830.0) <30 min/cont>	
Min. B- axis indexing increment		Number of tool stations					1		
Max. tool spindle speed min'		B-axis indexing time		S		0.85 [0.	55]/90°		
Tager hole of rotary tool spindle		Min. B-axis indexing increment				1° [0.0	0001°]		
Tool spindle Tool		Max. tool spindle speed		min-1		8,0	000		
Tool spindle Tool storage capacity		Taper hole of rotary tool spindle				Capto C8 [BT50*2] [CAT	T50] [HSK-A100 (T100)]		
Tool storage capacity		Type of retention knob			[DMG MORI SEIKI 90)°, Center through <mas dmg="" mor<="" td=""><td>I SEIKI 90°, CAT, DIN DMG MORI SE</td><td>KI 90°> (BT50 only)]</td></mas>	I SEIKI 90°, CAT, DIN DMG MORI SE	KI 90°> (BT50 only)]	
Max. tool diameter With adjacent tools		Inner diameter of rotary tool spindle	e bearing	mm (in.)		100	(3.9)		
Max. tool diameter Without adjacent tools mm (in.) 600 (23.6)	Tool spindle	Tool storage capacity				50 [100,	140, 180]		
Max. tool length		May tool diameter	With adjacent tools	mm (in.)		φ 120	(φ 4.7)		
Max. tool mass Mg (lb.)		max. tool diamotel	Without adjacent tools	mm (in.)		φ 250	(φ 9.8)		
Max. tool mass moment <from gauge="" line="" spindle=""> N-m (ft-lbf) (A tool with a mass moment greater than the maximum tool mass moment may cause problems during ATC operations even if it satisfies other conditions </from>		Max. tool length		mm (in.)		600 ((23.6)		
Max. tool mass moment									

[] Option *1 For the specifications of C-type, please contact DMG MORI SEIKI.

- *1 For the specifications of C-type, please contact DMG MORI SEIRI.

 *2 When selecting the two-face contact tool specification, be sure to use a two-face contact tool.

 Bar work capacity: Depending on the chuck/cylinder used and its restrictions, it may not be possible to reach full bar work capacity.

 Max. spindle speed: Depending on restrictions imposed by the workpiece clamping device, fixture and tool used, it may not be possible to rotate at the maximum spindle speed.

 ANR: ANR refers to a standard atmospheric state; i.e., temperature at 20°C (68°F); absolute pressure at 101.3 kPa (14.7 psi); and relative humidity at 65%.

 Power sources, machine size: the actual values may differ from those specified in the catalogue, depending on the optional features and peripheral equipment.

 Compressed air supply: Please be sure to supply clean compressed air air pressure: 0.7 MPa (101.5 psi), pressure dew point: 10°C (50°F) or below>.

 A criterion capacity to select a compressor is 90 L/min (23.8 gpm) per 0.75 kW (1 HP). However, this figure may differ depending on the type of compressors and options attached. For details, please check the compressor specifications.

 When the tool this air blow is required, supply of more than 300 L/min (79.2 gpm) is separately required.
- When the tool tip air blow is regularly used, air supply of more than 300 L/min (79.2 gpm) is separately required.

 Noise data: the measurement was performed at the front of the NT6600 DCG/6000s machine with a maximum spindle speed of 1,400 min⁻¹. For details, please consult with our sales representative.

 The information in this catalog is valid as of June 2013.

Machine specifications

	Item					DCG/4000			
				В	BS 1.070	(40.4)	CS		
	Max. swing of workpiece		mm (in.)		1,070	· · ·			
	Swing over cross slide		mm (in.)		1,070	, ,			
apacity	Max. distance between centers		mm (in.)	4,620 (181.8)	4,510 (177.5)	4,620 (181.8)	4,510 (177.5)		
apaony	Max. turning diameter		mm (in.)			(φ 42.1)			
	Max. turning length		mm (in.)		4,076	(160.4)			
	Bar work capacity		mm (in.)	164 (6.4)	164 (6.4)/164 (6.4) <spindle 2=""></spindle>	*	1		
	X-axis travel <tool spindle=""></tool>		mm (in.)		1,040 (40.9) <1,00	0(39.4)+40(1.6)>			
	Y-axis travel <tool spindle=""></tool>		mm (in.)		±330 (13.0)/+330 — -280 (1	3.0—11.0) <lbb specifications=""></lbb>			
	Z-axis travel <tool spindle=""></tool>		mm (in.)	4,150 (163.4)					
	B-axis rotation range <tool spindle<="" td=""><td></td><td> ()</td><td></td><td colspan="5">±120°</td></tool>		()		±120°				
	B-axis rotation range < roof spiriture	~			3,500 (137.8) <without></without>	20	3,500 (137.8) <without></without>		
ravel	Z-axis travel (Spindle 2) <steady< td=""><td>rest></td><td>mm (in.)</td><td>-</td><td>3,440 (135.4) <1> 2,870 (113.0) <2></td><td>-</td><td>3,440 (135.4) <1> 2,870 (113.0) <2></td></steady<>	rest>	mm (in.)	-	3,440 (135.4) <1> 2,870 (113.0) <2>	-	3,440 (135.4) <1> 2,870 (113.0) <2>		
	Z-axis travel (Tailstock) <steady r<="" td=""><td>rest></td><td>mm (in.)</td><td>3,500 (137.8) <without, 1=""> 2,930 (115.4) <2></without,></td><td>-</td><td>3,500 (137.8) <without, 1=""> 2,930 (115.4) <2></without,></td><td>-</td></steady>	rest>	mm (in.)	3,500 (137.8) <without, 1=""> 2,930 (115.4) <2></without,>	-	3,500 (137.8) <without, 1=""> 2,930 (115.4) <2></without,>	-		
	XA, XB, XC-axis <steady rest=""></steady>		mm (in.)	60/25 (2.4/1.0) <slu-6z, k6.1="" specifications=""></slu-6z,>					
	ZA, ZB, ZC-axis <steady rest=""></steady>		mm (in.)		3,440 (135.4) <1>	2,870 (113.0) <2>			
	Max. spindle speed		min-1	1,5	500	1,0	000		
	Number of spindle speed ranges				2 (winding char	nge-over speed)			
	Type of spindle nose			IIQ I	A ₂ -15		A ₁ -20		
			mm (in.)		(7.3)	275 (
oindle 1	Through-spindle hole diameter		()	183	· ·		(10.0)		
	Min. spindle indexing increment				0.00		(14.0)		
	Spindle bearing inner diameter		mm (in.)		(10.2)		(14.2)		
	Spindle torque	Low speed	N·m (ft·lbf)	3,254/2,386 (2,400.0/1	1,759.8) <25%ED/cont>	6,784/5,574 (5,003.6/4	4,111.2) <30 min/cont>		
	opinale torque	High speed	N·m (ft·lbf)	1,447/1,061 (1,067.2/7	782.6) <25%ED/cont>	3,016/2,481 (2,224.5/1	1,830.0) <30 min/cont>		
	Max. spindle speed		min-¹	_	1,500	_	1,000		
	Number of spindle speed ranges			_	2 (winding change-over speed)	-	2 (winding change-over spe		
	Type of spindle nose			_	JIS A ₂ -15	_	JIS A ₁ -20		
	Through-spindle hole diameter		mm (in.)	_	185 (7.3)	_	275 (10.8)		
	Min. spindle indexing increment		11111 (111.)	_	0.0001°	_	0.0001°		
oindle 2			(°-)						
	Spindle bearing inner diameter		mm (in.)	=	260 (10.2)	_	360 (14.2)		
	Spindle torque	Low speed	N·m (ft·lbf)	-	3,254/2,386 (2,400.0/1,759.8) <25%ED/cont>	-	6,784/5,574 (5,003.6/4,111 <30 min/cont>		
		High speed	N·m (ft·lbf)	-	1,447/1,061 (1,067.2/782.6) <25%ED/cont>	-	3,016/2,481 (2,224.5/1,830 <30 min/cont>		
	Number of tool stations								
	B-axis indexing time		s		0.85 [0.	551/00°			
			0		0.03 [0.				
					10.10				
	Min. B-axis indexing increment				1° [0.0				
	Min. B-axis indexing increment Max. tool spindle speed		min-1		8,0	000			
	Min. B-axis indexing increment		min ⁻¹		8,0 Capto C8 [BT50*²] [CAT	000 [50] [HSK-A100 (T100)]			
	Min. B-axis indexing increment Max. tool spindle speed		min-1	[DMG MORI SEIKI 90	8,0	000 [50] [HSK-A100 (T100)]	KI 90°> (BT50 only)]		
	Min. B-axis indexing increment Max. tool spindle speed Taper hole of rotary tool spindle	e bearing	min·1	[DMG MORI SEIKI 90	8,0 Capto C8 [BT50*²] [CAT	000 [50] [HSK-A100 (T100)] SEIKI 90°, CAT, DIN DMG MORI SEI	KI 90°> (BT50 only)]		
ool spindle	Min. B-axis indexing increment Max. tool spindle speed Taper hole of rotary tool spindle Type of retention knob	e bearing		[DMG MORI SEIKI 90	8,0 Capto C8 [BT50*2] [CA7 O°, Center through <mas dmg="" mori<="" td=""><td>000 [750] [HSK-A100 (T100)] SEIKI 90°, CAT, DIN DMG MORI SEI (3.9)</td><td>IKI 90°> (BT50 only)]</td></mas>	000 [750] [HSK-A100 (T100)] SEIKI 90°, CAT, DIN DMG MORI SEI (3.9)	IKI 90°> (BT50 only)]		
ol spindle	Min. B-axis indexing increment Max. tool spindle speed Taper hole of rotary tool spindle Type of retention knob Inner diameter of rotary tool spindl Tool storage capacity	e bearing With adiacent tools		[DMG MORI SEIKI 90	8,0 Capto C8 (BT50*2) [CAT 0°, Center through <mas dmg="" mori<br="">100 50 [100,</mas>	000 [50] [HSK-A100 (T100)] SEIKI 90°, CAT, DIN DMG MORI SEI (3.9)	IKI 90°> (BT50 only)]		
ool spindle	Min. B-axis indexing increment Max. tool spindle speed Taper hole of rotary tool spindle Type of retention knob Inner diameter of rotary tool spindl	With adjacent tools	mm (in.)	[DMG MORI SEIKI 90	8,0 Capto C8 [BT50*2] [CAT 0°, Center through <mas dmg="" mori<br="">100 50 [100, φ 120</mas>	1000 [50] [HSK-A100 (T100)] SEIKI 90°, CAT, DIN DMG MORI SEI (3.9) 140, 180] (φ 4.7)	IKI 90°> (BT50 only)]		
ool spindle	Min. B-axis indexing increment Max. tool spindle speed Taper hole of rotary tool spindle Type of retention knob Inner diameter of rotary tool spindl Tool storage capacity Max. tool diameter		mm (in.) mm (in.) mm (in.)	[DMG MORI SEIKI 90	8,0 Capto C8 [BT50*2] [CAT Capto C8 [BT50*2] [CAT CAPTO C8 [BT50*2] [CAT CAPTO C8 [BT50*2] [CAT C4P C8 C4P	1000 150] [HSK-A100 (T100)] SEIKI 90°, CAT, DIN DMG MORI SEI (3.9) 140, 180] (φ 4.7) (φ 9.8)	IKI 90°> (BT50 only)]		
ool spindle	Min. B-axis indexing increment Max. tool spindle speed Taper hole of rotary tool spindle Type of retention knob Inner diameter of rotary tool spindl Tool storage capacity Max. tool diameter Max. tool length	With adjacent tools	mm (in.) mm (in.) mm (in.) mm (in.)	[DMG MORI SEIKI 90	8,0 Capto C8 [BT50*2] [CAT 0°, Center through < MAS DMG MORI 100 50 [100, \$\phi\$ 120 \$\phi\$ 250 600 (000 (50) [HSK-A100 (T100)] SEIKI 90°, CAT, DIN DMG MORI SEI (3.9) (40, 180) (40, 47) (40, 9.8) (40, 9.8) (40, 9.8)	IKI 90°> (BT50 only)]		
ool spindle	Min. B-axis indexing increment Max. tool spindle speed Taper hole of rotary tool spindle Type of retention knob Inner diameter of rotary tool spindl Tool storage capacity Max. tool diameter	With adjacent tools	mm (in.) mm (in.) mm (in.)	[DMG MORI SEIKI 90	8,0 Capto C8 [BT50*2] [CAT 0°, Center through < MAS DMG MORI 100 50 [100, \$\phi\$ 120 \$\phi\$ 250 600 (\$\frac{1}{3}\$)	000 (150) [HSK-A100 (T100)] SEIKI 90°, CAT, DIN DMG MORI SEI (3.9) 140, 180] (6 4.7) (6 9.8) 23.6) (66)	IKI 90°> (BT50 only)]		
ol spindle	Min. B-axis indexing increment Max. tool spindle speed Taper hole of rotary tool spindle Type of retention knob Inner diameter of rotary tool spindl Tool storage capacity Max. tool diameter Max. tool length	With adjacent tools Without adjacent tools	mm (in.) mm (in.) mm (in.) mm (in.)		8,0 Capto C8 [BT50*2] [CAT 0°, Center through < MAS DMG MORI 100 50 [100, \$\phi\$ 120 \$\phi\$ 250 600 (30)	1000 150] [HSK-A100 (T100)] SEIKI 90°, CAT, DIN DMG MORI SEI (3.9) 140, 180] (φ 4.7) (φ 9.8) 23.6) 166) (21.6)			
ol spindle	Min. B-axis indexing increment Max. tool spindle speed Taper hole of rotary tool spindle Type of retention knob Inner diameter of rotary tool spindl Tool storage capacity Max. tool diameter Max. tool length Max. tool mass Max. tool mass moment < from spi	With adjacent tools Without adjacent tools India gauge line	mm (in.) mm (in.) mm (in.) mm (in.) kg (ib.) N·m (ft·lbf)		8,0 Capto C8 [BT50*2] [CAT C8 [BT50*2] [CAT 100 C8 [BT50*2] [CAT 100 C50 [100,	150] [HSK-A100 (T100)] SEIKI 90°, CAT, DIN DMG MORI SEI (3.9) 140, 180] (\$\phi \ 4.7\$) (\$\phi \ 9.8\$) 23.6} [66] [21.6] ay cause problems during ATC operation			
ol spindle	Min. B-axis indexing increment Max. tool spindle speed Taper hole of rotary tool spindle Type of retention knob Inner diameter of rotary tool spindl Tool storage capacity Max. tool diameter Max. tool length Max. tool mass	With adjacent tools Without adjacent tools India gauge line	mm (in.) mm (in.) mm (in.) mm (in.) kg (lb.)		8,0 Capto C8 [BT50*2] [CAT 0°, Center through < MAS DMG MORI 100 50 [100, \$\phi\$ 120 \$\phi\$ 250 600 (30)	1000 150] [HSK-A100 (T100)] SEIKI 90°, CAT, DIN DMG MORI SEI (3.9) 140, 180] (φ 4.7) (φ 9.8) 23.6) (66) (21.6) ay cause problems during ATC operation (2.7/129.1/108.4)			
ol spindle	Min. B-axis indexing increment Max. tool spindle speed Taper hole of rotary tool spindle Type of retention knob Inner diameter of rotary tool spindl Tool storage capacity Max. tool diameter Max. tool length Max. tool mass Max. tool mass moment < from spi	With adjacent tools Without adjacent tools India gauge line	mm (in.) mm (in.) mm (in.) mm (in.) kg (ib.) N·m (ft·lbf)		8,0 Capto C8 [BT50*2] [CAT C8 [BT50*2] [CAT C9 C8 [BT50*2] [CAT C9 C9 C8 [BT50*2] [CAT C9 C9 C8	150] [HSK-A100 (T100)] SEIKI 90°, CAT, DIN DMG MORI SEI (3.9) 140, 180] (\$\phi \ 4.7\$) (\$\phi \ 9.8\$) 23.6} [66] [21.6] ay cause problems during ATC operation			
	Min. B-axis indexing increment Max. tool spindle speed Taper hole of rotary tool spindle Type of retention knob Inner diameter of rotary tool spindl Tool storage capacity Max. tool diameter Max. tool length Max. tool mass Max. tool mass moment <from 15="" <15%ed="" min="" or<="" spi="" spindle="" td="" torque=""><td>With adjacent tools Without adjacent tools India gauge line</td><td>mm (in.) mm (in.) mm (in.) mm (in.) kg (lb.) N·m (ft·lbf)</td><td>(A tool with a mass moment greater th</td><td>8,0 Capto C8 [BT50*2] [CAT C8 [BT50*2] [CAT C9 C8 [BT50*2] [CAT C9 C9 C8 [BT50*2] [CAT C9 C9 C8 C8</td><td>1000 150] [HSK-A100 (T100)] SEIKI 90°, CAT, DIN DMG MORI SEI (3.9) 140, 180] (φ 4.7) (φ 9.8) 23.6) (66) (21.6) ay cause problems during ATC operation (2.7/129.1/108.4)</td><td></td></from>	With adjacent tools Without adjacent tools India gauge line	mm (in.) mm (in.) mm (in.) mm (in.) kg (lb.) N·m (ft·lbf)	(A tool with a mass moment greater th	8,0 Capto C8 [BT50*2] [CAT C8 [BT50*2] [CAT C9 C8 [BT50*2] [CAT C9 C9 C8 [BT50*2] [CAT C9 C9 C8	1000 150] [HSK-A100 (T100)] SEIKI 90°, CAT, DIN DMG MORI SEI (3.9) 140, 180] (φ 4.7) (φ 9.8) 23.6) (66) (21.6) ay cause problems during ATC operation (2.7/129.1/108.4)			
	Min. B-axis indexing increment Max. tool spindle speed Taper hole of rotary tool spindle Type of retention knob Inner diameter of rotary tool spindl Tool storage capacity Max. tool diameter Max. tool length Max. tool mass Max. tool mass moment <from 15="" <15%ed="" cd="" diameter<="" min="" spi="" spindle="" tailstock="" td="" torque=""><td>With adjacent tools Without adjacent tools India gauge line</td><td>mm (in.) mm (in.) mm (in.) mm (in.) kg (lb.) N·m (ft·lbf)</td><td>(A tool with a mass moment greater the state of the state</td><td>8,0 Capto C8 [BT50*2] [CAT 100 C8 [BT50*2] [CAT 100 C50 [100, \$\phi\$ 120 \$\phi\$ 250 \$\phi\$ 600 (30 iii) 29.4 than the maximum tool mass moment m 302/175/147 (22</td><td>1000 150] [HSK-A100 (T100)] SEIKI 90°, CAT, DIN DMG MORI SEI (3.9) (40 4.7) (40 9.8) 23.6) (66) (21.6) (21.7) (22.7/129.1/108.4) 150 (5.9) [180 (7.1)]</td><td></td></from>	With adjacent tools Without adjacent tools India gauge line	mm (in.) mm (in.) mm (in.) mm (in.) kg (lb.) N·m (ft·lbf)	(A tool with a mass moment greater the state of the state	8,0 Capto C8 [BT50*2] [CAT 100 C8 [BT50*2] [CAT 100 C50 [100, \$\phi\$ 120 \$\phi\$ 250 \$\phi\$ 600 (30 iii) 29.4 than the maximum tool mass moment m 302/175/147 (22	1000 150] [HSK-A100 (T100)] SEIKI 90°, CAT, DIN DMG MORI SEI (3.9) (40 4.7) (40 9.8) 23.6) (66) (21.6) (21.7) (22.7/129.1/108.4) 150 (5.9) [180 (7.1)]			
iilstock	Min. B-axis indexing increment Max. tool spindle speed Taper hole of rotary tool spindle Type of retention knob Inner diameter of rotary tool spindl Tool storage capacity Max. tool diameter Max. tool length Max. tool mass Max. tool mass moment <from 15="" <15%ed="" ci="" diameter="" hole="" min="" of="" spi="" spindle="" spindle<="" tailstock="" taper="" td="" torque=""><td>With adjacent tools Without adjacent tools India gauge line</td><td>mm (in.) mm (in.) mm (in.) mm (in.) kg (lb.) N·m (ft-lbf) N·m (ft-lbf) mm (in.)</td><td>(A tool with a mass moment greater the state of the state</td><td>8,6 Capto C8 [BT50*2] [CAT 0°, Center through < MAS DMG MORI 100 50 [100, \$\phi\$ 120 \$\phi\$ 250 600 (30 () 29.4 () han the maximum tool mass moment m: 302/175/147 (22</td><td>1500 [HSK-A100 (T100)] SEIKI 90°, CAT, DIN DMG MORI SEI (3.9) 140, 180] (\$\phi \text{ 4.7}\$) (\$\phi \text{ 9.8}\$) 23.6) (66) (21.6) 22.7/129.1/108.4) 150 (5.9) [180 (7.1)] MTS [MT6] < Built-in> 150 (5.9) Tailstock A: 8 (26.2) Steady rest XA, X</td><td>ns even if it satisfies other condit</td></from>	With adjacent tools Without adjacent tools India gauge line	mm (in.) mm (in.) mm (in.) mm (in.) kg (lb.) N·m (ft-lbf) N·m (ft-lbf) mm (in.)	(A tool with a mass moment greater the state of the state	8,6 Capto C8 [BT50*2] [CAT 0°, Center through < MAS DMG MORI 100 50 [100, \$\phi\$ 120 \$\phi\$ 250 600 (30 () 29.4 () han the maximum tool mass moment m: 302/175/147 (22	1500 [HSK-A100 (T100)] SEIKI 90°, CAT, DIN DMG MORI SEI (3.9) 140, 180] (\$\phi \text{ 4.7}\$) (\$\phi \text{ 9.8}\$) 23.6) (66) (21.6) 22.7/129.1/108.4) 150 (5.9) [180 (7.1)] MTS [MT6] < Built-in> 150 (5.9) Tailstock A: 8 (26.2) Steady rest XA, X	ns even if it satisfies other condit		
pol spindle ailstock eedrate	Min. B-axis indexing increment Max. tool spindle speed Taper hole of rotary tool spindle Type of retention knob Inner diameter of rotary tool spindl Tool storage capacity Max. tool diameter Max. tool length Max. tool mass Max. tool mass Max. tool mass moment <from 15="" <15%ed="" cd="" diameter="" hole="" min="" of="" spi="" spindle="" tailstock="" taper="" td="" torque="" travel<=""><td>With adjacent tools Without adjacent tools India gauge line</td><td>mm (in.) mm (in.) mm (in.) mm (in.) kg (ib.) N-m (ft-lbf) mm (in.) mm (in.)</td><td>(A tool with a mass moment greater the state of the state</td><td>8,0 Capto C8 [BT50*2] [CAT Capto C8 [BT50*2] [CAT 100 S0 [100, \$\phi\$ 120 \$\phi\$ 250 \$\phi\$ 600 \$\phi\$ 30 \$\phi\$ 140 \$\phi\$ 29.4 \$\phi\$ an the maximum tool mass moment m 302/175/147 (22 \$\phi\$ 2.32 (105.0) Spindle 2 A: 15 (49.2) \$\phi\$ 23.8 [80 <full 30="" cont="" e25%="" ed="" indexing="" min=""></full></td><td>1500 [HSK-A100 (T100)] SEIKI 90°, CAT, DIN DMG MORI SEI (3.9) 140, 180] (\$\phi \text{ 4.7}\$) (\$\phi \text{ 9.8}\$) 23.6) (66) (21.6) 22.7/129.1/108.4) 150 (5.9) [180 (7.1)] MTS [MT6] < Built-in> 150 (5.9) Tailstock A: 8 (26.2) Steady rest XA, X</td><td>ns even if it satisfies other conditi — — — — XB, XC: 1.6 (5.2) ZA, ZB, ZC: 8 (2</td></from>	With adjacent tools Without adjacent tools India gauge line	mm (in.) mm (in.) mm (in.) mm (in.) kg (ib.) N-m (ft-lbf) mm (in.) mm (in.)	(A tool with a mass moment greater the state of the state	8,0 Capto C8 [BT50*2] [CAT Capto C8 [BT50*2] [CAT 100 S0 [100, \$\phi\$ 120 \$\phi\$ 250 \$\phi\$ 600 \$\phi\$ 30 \$\phi\$ 140 \$\phi\$ 29.4 \$\phi\$ an the maximum tool mass moment m 302/175/147 (22 \$\phi\$ 2.32 (105.0) Spindle 2 A: 15 (49.2) \$\phi\$ 23.8 [80 <full 30="" cont="" e25%="" ed="" indexing="" min=""></full>	1500 [HSK-A100 (T100)] SEIKI 90°, CAT, DIN DMG MORI SEI (3.9) 140, 180] (\$\phi \text{ 4.7}\$) (\$\phi \text{ 9.8}\$) 23.6) (66) (21.6) 22.7/129.1/108.4) 150 (5.9) [180 (7.1)] MTS [MT6] < Built-in> 150 (5.9) Tailstock A: 8 (26.2) Steady rest XA, X	ns even if it satisfies other conditi — — — — XB, XC: 1.6 (5.2) ZA, ZB, ZC: 8 (2		
nilstock	Min. B-axis indexing increment Max. tool spindle speed Taper hole of rotary tool spindle Type of retention knob Inner diameter of rotary tool spindl Tool storage capacity Max. tool diameter Max. tool length Max. tool mass Max. tool mass moment <from 15="" <15%ed="" diameter="" hole="" min="" of="" or="" rapid="" rate<="" spi="" spindle="" tailstock="" taper="" td="" torque="" travel="" traverse=""><td>With adjacent tools Without adjacent tools India gauge line</td><td>mm (in.) mm (in.) mm (in.) mm (in.) kg (ib.) N-m (ft-lbf) mm (in.) mm (in.) mm (in.)</td><td>(A tool with a mass moment greater the state of the state</td><td>8,0 Capto C8 [BT50*2] [CAT Capto C8 [BT50*2] [CAT C4 C8 [BT50*2] [CAT C4 C8 [BT50*2] [CAT C4 C8 C8</td><td>1000 150] [HSK-A100 (T100)] SEIKI 90°, CAT, DIN DMG MORI SEI (3.9) 140, 180] (φ 4.7) (φ 9.8) 23.6) (66) (21.6) ay cause problems during ATC operation 2.7/129.1/108.4) 150 (5.9) [180 (7.1)] MT5 [MT6] < Built-in> 150 (5.9) Tailstock A: 8 (26.2) Steady rest XA, 2 a pecifications>] C: 70</td><td>ns even if it satisfies other conditi ———————————————————————————————————</td></from>	With adjacent tools Without adjacent tools India gauge line	mm (in.) mm (in.) mm (in.) mm (in.) kg (ib.) N-m (ft-lbf) mm (in.) mm (in.) mm (in.)	(A tool with a mass moment greater the state of the state	8,0 Capto C8 [BT50*2] [CAT Capto C8 [BT50*2] [CAT C4 C8 [BT50*2] [CAT C4 C8 [BT50*2] [CAT C4 C8	1000 150] [HSK-A100 (T100)] SEIKI 90°, CAT, DIN DMG MORI SEI (3.9) 140, 180] (φ 4.7) (φ 9.8) 23.6) (66) (21.6) ay cause problems during ATC operation 2.7/129.1/108.4) 150 (5.9) [180 (7.1)] MT5 [MT6] < Built-in> 150 (5.9) Tailstock A: 8 (26.2) Steady rest XA, 2 a pecifications>] C: 70	ns even if it satisfies other conditi ———————————————————————————————————		
nilstock	Min. B-axis indexing increment Max. tool spindle speed Taper hole of rotary tool spindle Type of retention knob Inner diameter of rotary tool spindl Tool storage capacity Max. tool diameter Max. tool length Max. tool mass Max. tool mass Max. tool mass Max. tool mass Max. tool mass Max. tool mass moment <from 1="" 15="" <15%ed="" diameter="" drive="" hole="" min="" motor<="" of="" or="" rapid="" rate="" spi="" spindle="" tailstock="" taper="" td="" torque="" travel="" traverse=""><td>With adjacent tools Without adjacent tools mithout adjacent tools ndle gauge line></td><td>mm (in.) mm (in.) mm (in.) mm (in.) kg (ib.) N-m (ft-lbf) mm (in.) mm (in.) mm (in.) kg (ib.) kg (ib.)</td><td>(A tool with a mass moment greater the state of the state</td><td>8,0 Capto C8 [BT50*2] [CAI Capto C8 [BT50*2] [CAI CAI C8 [BT50*2] [CAI C90, Center through < MAS DMG MORI 100 50 [100, \$\phi\$ 120 \$\phi\$ 250 600 (\$\phi\$ 30 (\$\phi\$ 29.4 \phi\$ an the maximum tool mass moment m 302/175/147 (22 \$\phi\$ - \$\phi\$ \$\phi\$ \$\phi\$ 23.8 [80 < Full indexing < 25% ED/30 min/cont> 30/26/22 (40/34.7/30)</td><td>(3.9) (4.6) (5.6) [HSK-A100 (T100)] (5.6) [HSK-A100 (T100)] (5.8) [HSK-A100 (T100)] (6.9) (9.8)</td><td>ns even if it satisfies other conditi — — ——————————————————————————————</td></from>	With adjacent tools Without adjacent tools mithout adjacent tools ndle gauge line>	mm (in.) mm (in.) mm (in.) mm (in.) kg (ib.) N-m (ft-lbf) mm (in.) mm (in.) mm (in.) kg (ib.) kg (ib.)	(A tool with a mass moment greater the state of the state	8,0 Capto C8 [BT50*2] [CAI Capto C8 [BT50*2] [CAI CAI C8 [BT50*2] [CAI C90, Center through < MAS DMG MORI 100 50 [100, \$\phi\$ 120 \$\phi\$ 250 600 (\$\phi\$ 30 (\$\phi\$ 29.4 \phi\$ an the maximum tool mass moment m 302/175/147 (22 \$\phi\$ - \$\phi\$ \$\phi\$ \$\phi\$ 23.8 [80 < Full indexing < 25% ED/30 min/cont> 30/26/22 (40/34.7/30)	(3.9) (4.6) (5.6) [HSK-A100 (T100)] (5.6) [HSK-A100 (T100)] (5.8) [HSK-A100 (T100)] (6.9) (9.8)	ns even if it satisfies other conditi — — ——————————————————————————————		
ilstock edrate	Min. B-axis indexing increment Max. tool spindle speed Taper hole of rotary tool spindle Type of retention knob Inner diameter of rotary tool spindl Tool storage capacity Max. tool diameter Max. tool length Max. tool mass Max. tool mass moment <from 1="" 15="" <15%ed="" cd="" diameter="" drive="" hole="" min="" motor<="" of="" rapid="" rate="" spi="" spindle="" tailstock="" taper="" td="" torque="" travel="" traverse=""><td>With adjacent tools Without adjacent tools mithout adjacent tools ndle gauge line></td><td>mm (in.) mm (in.) mm (in.) mm (in.) kg (ib.) N-m (ft-lbf) mm (in.) mm (in.) m/min (fpm) min· kW (HP)</td><td>(A tool with a mass moment greater the state of the state</td><td>8,6 Capto C8 [BT50*2] [CAT 100 50 [100,</td><td>(3.9) (4.6) (5.6) [HSK-A100 (T100)] (5.6) [HSK-A100 (T100)] (5.8) [HSK-A100 (T100)] (6.9) (9.8)</td><td>ns even if it satisfies other condit </td></from>	With adjacent tools Without adjacent tools mithout adjacent tools ndle gauge line>	mm (in.) mm (in.) mm (in.) mm (in.) kg (ib.) N-m (ft-lbf) mm (in.) mm (in.) m/min (fpm) min· kW (HP)	(A tool with a mass moment greater the state of the state	8,6 Capto C8 [BT50*2] [CAT 100 50 [100,	(3.9) (4.6) (5.6) [HSK-A100 (T100)] (5.6) [HSK-A100 (T100)] (5.8) [HSK-A100 (T100)] (6.9) (9.8)	ns even if it satisfies other condit		
ilstock edrate otors	Min. B-axis indexing increment Max. tool spindle speed Taper hole of rotary tool spindle Type of retention knob Inner diameter of rotary tool spindl Tool storage capacity Max. tool diameter Max. tool length Max. tool mass Max. tool mass moment <from 1="" 15="" 2="" 50hz="" <15%ed="" <30="" <60="" coolant="" diameter="" drive="" hole="" min="" motor="" of="" or="" pump="" rapid="" rate="" spi="" spindle="" tailstock="" taper="" tool="" torque="" travel="" traverse=""></from>	With adjacent tools Without adjacent tools mithout adjacent tools ndle gauge line>	mm (in.) mm (in.) mm (in.) mm (in.) kg (ib.) N-m (ft-lbf) mm (in.) mm (in.) mm (in.) kW (HP) kW (HP) kW (HP)	(A tool with a mass moment greater to 150 (5.9) [180 (7.1)] MT5 [MT6] < Built-in> 150 (5.9) Tool spindle X: 40 (131.2), Y: 30 (98.4) 30/26/22 (40/34.7/30)	8,0 Capto C8 [BT50*2] [CAT Capto C8 [BT50*2] [CAT CAPTO C8 [BT50*2] [CAT CAPTO C8 [BT50*2] [CAT C9 CAPTO C9 C9 CAPTO C9 CAPTO C9 CAPTO C9	1500 (150) [HSK-A100 (T100)] SEIKI 90°, CAT, DIN DMG MORI SEI (3.9) 140, 180] (φ 4.7) (φ 9.8) 23.6) (66) (21.6) ay cause problems during ATC operation (2.7/129.1/108.4) 150 (5.9) [180 (7.1)] MT5 [MT6] < Built-in> 150 (5.9) Tailstock A: 8 (26.2) Steady rest XA, XB (26.2) Steady rest X	ns even if it satisfies other conditions even if it satisfies other conditions are seven if it satisfies other conditions.		
eedrate otors	Min. B-axis indexing increment Max. tool spindle speed Taper hole of rotary tool spindle Type of retention knob Inner diameter of rotary tool spindl Tool storage capacity Max. tool diameter Max. tool length Max. tool mass Max. tool	With adjacent tools Without adjacent tools indle gauge line> ont>	mm (in.) mm (in.) mm (in.) mm (in.) kg (ib.) N-m (ft-lbf) mm (in.) mm (in.) mm (in.) m/min (fpm) kW (HP) kW (HP) kW (HP)	(A tool with a mass moment greater the state of the state	8,0 Capto C8 [BT50*2] [CAT 100 50 [100, \$\phi\$ 120 \$\phi\$ 250 600 (30 () 29.4 than the maximum tool mass moment m 302/175/147 (22 \$	1000 1500	ns even if it satisfies other condit		
eedrate otors ower sources standard)	Min. B-axis indexing increment Max. tool spindle speed Taper hole of rotary tool spindle Type of retention knob Inner diameter of rotary tool spindl Tool storage capacity Max. tool length Max. tool length Max. tool mass Max. tool m	With adjacent tools Without adjacent tools indle gauge line> ont>	mm (in.) mm (in.) mm (in.) mm (in.) mm (in.) kg (ib.) N-m (ft-lbf) mm (in.) mm (in.) kW (HP) kW (HP) kW (HP) kW (HP)	(A tool with a mass moment greater to 150 (5.9) [180 (7.1)] MT5 [MT6] < Built-in> 150 (5.9) Tool spindle X: 40 (131.2), Y: 30 (98.4) 30/26/22 (40/34.7/30)	8,0 Capto C8 [BT50*2] [CAT 100 50 [100, \$\phi\$ 120 \$\phi\$ 250 600 (30 () 40 () 30 () 40 () 30 () 30 () 40 () 30 () 30 () 30 () 40 () 30 () 30 () 30 () 40 () 30 () 30 () 30 () 30 () 30 () 30 () 30 () 30 () 30 () 30 () 30 () 30 () 30 () 30 () 30 () 30 () 410 () 30 () 410 () 4	1500 [HSK-A100 (T100)] SEIKI 90°, CAT, DIN DMG MORI SEI (3.9) (40, 180] (φ 4.7) (φ 9.8) 23.6) (66) (21.6) 39, cause problems during ATC operation (2.7/129.1/108.4) 150 (5.9) [180 (7.1)] MT5 [MT6] < Built-in> 150 (5.9) Tailstock A: 8 (26.2) Steady rest XA, 3 3 specifications>] C: 70 45/37 (60/50) (40/30) 0.635 (0.85)>×1 1.5 (2.0) <0.75 84.5 (237.6) <anr></anr>	ns even if it satisfies other condition		
eedrate otors ower sources standard)	Min. B-axis indexing increment Max. tool spindle speed Taper hole of rotary tool spindle Type of retention knob Inner diameter of rotary tool spindl Tool storage capacity Max. tool diameter Max. tool length Max. tool mass Max. tool mass moment <from 1="" 15="" 2="" 50hz="" <15%ed="" <30="" <60="" c="" cd="" coolant="" diameter="" drive="" hole="" min="" motor="" of="" pump="" rapid="" rate="" spi="" spindle="" tailstock="" taper="" tool="" torque="" travel="" traverse=""> Electrical power supply <cont> Compressed air supply Coolant tank capacity</cont></from>	With adjacent tools Without adjacent tools indle gauge line> ont>	mm (in.) mm (in.) mm (in.) mm (in.) kg (ib.) N-m (ft-lbf) mm (in.) m/min (fpm) min-kW (HP) kW (HP) kW (HP) kW (HP) kV (HP) kV (HP) kV (HP) kV (HP)	(A tool with a mass moment greater the state of the state	8,0 Capto C8 [BT50*2] [CAT 100 50 [100, \$\phi\$ 120 \$\phi\$ 250 600 (30 (30 (29.4) han the maximum tool mass moment m 302/175/147 (22	1500 [HSK-A100 (T100)] SEIKI 90°, CAT, DIN DMG MORI SEI (3.9) (40 4.7) (φ 9.8) 23.6) (66) (21.6) 3y cause problems during ATC operation (2.7/129.1/108.4) 150 (5.9) [180 (7.1)] MT5 [MT6] < Built-in> 150 (5.9) Tailstock A: 8 (26.2) Steady rest XA, λ 2 specifications>] C: 70 45/37 (60/50) (40/30) .635 (0.85) × 1 1.5 (2.0) < 0.75 84.5 (237.6) < ANR> 356.4)	ns even if it satisfies other condition		
ailstock eedrate otors ower sources standard) ink capacity	Min. B-axis indexing increment Max. tool spindle speed Taper hole of rotary tool spindle Type of retention knob Inner diameter of rotary tool spindl Tool storage capacity Max. tool diameter Max. tool length Max. tool mass Max. tool mass Max. tool mass moment <from 1="" 15="" 2="" 50hz="" <15%ed="" <60="" cd="" coolant="" diameter="" drive="" hole="" min="" motor="" of="" pump="" rapid="" rate="" spi="" spindle="" tailstock="" taper="" tool="" torque="" travel="" traverse=""> Electrical power supply <cont> Compressed air supply Coolant tank capacity Machine height <from floor=""></from></cont></from>	With adjacent tools Without adjacent tools indle gauge line> ont>	mm (in.) mm (in.) mm (in.) mm (in.) kg (ib.) N-m (ft-lbf) mm (in.) mm (in.) kW (HP) kW (HP) kW (HP) kW (HP) kVA), L/min (gpn) L (gal.) mm (in.)	(A tool with a mass moment greater the state of the state	8,0 Capto C8 [BT50*2] [CAI Capto C8 [BT50*2] [CAI C8 [BT50*2] [CAI C9 C8 [BT50*2] [CAI C9 C8 [BT50*2] [CAI C9 C8 [BT50*2] [CAI C9 C8 C9	500 (500) [HSK-A100 (T100)] SEIKI 90°, CAT, DIN DMG MORI SEI (3.9) (3.9) (40, 18)	ns even if it satisfies other conditions even if it satisfies other conditions of the conditions of th		
ailstock	Min. B-axis indexing increment Max. tool spindle speed Taper hole of rotary tool spindle Type of retention knob Inner diameter of rotary tool spindl Tool storage capacity Max. tool diameter Max. tool diameter Max. tool mass Max. tool mass Max. tool mass moment <from 1="" 15="" 2="" 50hz="" <15%ed="" <30="" <60="" c="" ci="" coolant="" diameter="" drive="" hole="" min="" motor="" of="" pump="" rapid="" rate="" spi="" spindle="" tailstock="" taper="" tool="" torque="" travel="" traverse=""> Electrical power supply <cont> Compressed air supply Coolant tank capacity Machine height <from floor=""> Floor space <width depth="" ×=""></width></from></cont></from>	With adjacent tools Without adjacent tools indle gauge line> ont>	mm (in.) mm (in.) mm (in.) mm (in.) kg (ib.) N-m (ft-lbf) mm (in.) mm (in.) mm (in.) kW (HP) kW (HP) kW (HP) kVA), L/min (gpm) L (gat.) mm (in.)	(A tool with a mass moment greater the state of the state	8,0 Capto C8 [BT50*2] [CAT Capto C8 [BT50*2] [CAT 100 50 [100, \$ 120 \$ 250 600 (30 () 4 120 29.4 4 han the maximum tool mass moment m 302/175/147 (22 — — ———————————————————————————————	1500 [HSK-A100 (T100)] SEIKI 90°, CAT, DIN DMG MORI SEI (3.9) (40, 180] (φ 4.7) (φ 9.8) 23.6) (66) (21.6) 22.7(129.1/108.4) 150 (5.9) [180 (7.1)] MT5 [MT6] < Built-in> 150 (5.9) Tailstock A: 8 (26.2) Steady rest XA, 2 3 specifications> C: 70 45/37 (60/50) (40/30) 0.635 (0.85)>×1 1.5 (2.0) <0.75 84.5 (23.6) <anr> 336.4) Scraper type+Drum filter: 4,316 (1</anr>	ns even if it satisfies other condition		
ailstock eedrate otors ower sources standard) ink capacity	Min. B-axis indexing increment Max. tool spindle speed Taper hole of rotary tool spindle Type of retention knob Inner diameter of rotary tool spindl Tool storage capacity Max. tool diameter Max. tool length Max. tool mass Max. tool mass Max. tool mass moment <from 1="" 15="" 2="" 50hz="" <15%ed="" <60="" cd="" coolant="" diameter="" drive="" hole="" min="" motor="" of="" pump="" rapid="" rate="" spi="" spindle="" tailstock="" taper="" tool="" torque="" travel="" traverse=""> Electrical power supply <cont> Compressed air supply Coolant tank capacity Machine height <from floor=""></from></cont></from>	With adjacent tools Without adjacent tools indle gauge line> ont>	mm (in.) mm (in.) mm (in.) mm (in.) kg (ib.) N-m (ft-lbf) mm (in.) mm (in.) kW (HP) kW (HP) kW (HP) kW (HP) kVA), L/min (gpn) L (gal.) mm (in.)	(A tool with a mass moment greater the state of the state	8,0 Capto C8 [BT50*2] [CAI Capto C8 [BT50*2] [CAI C8 [BT50*2] [CAI C9 C8 [BT50*2] [CAI C9 C8 [BT50*2] [CAI C9 C8 [BT50*2] [CAI C9 C8 C9	500 (500) [HSK-A100 (T100)] SEIKI 90°, CAT, DIN DMG MORI SEI (3.9) (3.9) (40, 18)	ns even if it satisfies other condition		

*1 For the specifications of C-type, please contact DMG MORI SEIKI.

- *2 When selecting the two-face contact tool specification, be sure to use a two-face contact tool.
- ** 2 when selecting the two-lace contact tools pechlication, be sure to use a two-lace contact tool.
 Bar work capacity: Depending on the chuck/cylinder used and its restrictions, it may not be possible to reach full bar work capacity.
 Max. spindle speed: Depending on restrictions imposed by the workpiece clamping device, fixture and tool used, it may not be possible to rotate at the maximum spindle speed.
 ANR: ANR refers to a standard atmospheric state; i.e., temperature at 20°C (68°F); absolute pressure at 101.3 kPa (14.7 psi); and relative humidity at 65%.
 Power sources, machine size: the actual values may differ from those specified in the catalogue, depending on the optional features and peripheral equipment.

			NT6600 DCG/6000				
	Item		В	BS	С	cs	
	Max. swing of workpiece	mm (in.		1,070	(42.1)		
	Swing over cross slide	mm (in.		1,070	(42.1)		
0	Max. distance between centers	mm (in.	6,620 (260.6)	6,510 (256.2)	6,620 (260.6)	6,510 (256.2)	
Capacity	Max. turning diameter mm (in.)		φ 1,070 (φ 42.1)				
	Max. turning length	mm (in.	6,076 (239.2)				
	Bar work capacity	mm (in.	164 (6.4)	164 (6.4)/164 (6.4) <spindle 2=""></spindle>	*	:1	
	X-axis travel <tool spindle=""></tool>	mm (in.		1,040 (40.9) <1,00	0(39.4)+40(1.6)>		
	Y-axis travel <tool spindle=""></tool>	mm (in.		±330 (13.0)/+330 — -280 (1	3.0—11.0) <lbb specifications=""></lbb>		
	Z-axis travel <tool spindle=""></tool>	mm (in.		6,150	(242.1)		
	B-axis rotation range <tool spind<="" td=""><td>le></td><td></td><td>±1</td><td>20°</td><td></td></tool>	le>		±1	20°		
Travel	Z-axis travel (Spindle 2) <steady< td=""><td>rest> mm (in.</td><td>_</td><td>4,870 (191.7) <2> 4,310 (169.7) <3></td><td>_</td><td>4,870 (191.7) <2> 4,310 (169.7) <3></td></steady<>	rest> mm (in.	_	4,870 (191.7) <2> 4,310 (169.7) <3>	_	4,870 (191.7) <2> 4,310 (169.7) <3>	
	Z-axis travel (Tailstock) <steady< td=""><td>rest> mm (in.</td><td>4,930 (194.1) <2> 4,460 (175.6) <3></td><td>_</td><td>4,930 (194.1) <2> 4,460 (175.6) <3></td><td>_</td></steady<>	rest> mm (in.	4,930 (194.1) <2> 4,460 (175.6) <3>	_	4,930 (194.1) <2> 4,460 (175.6) <3>	_	
	XA, XB, XC-axis <steady rest=""></steady>	mm (in.		60/25 (2.4/1.0) <slu-6< td=""><td>6Z, K6.1 specifications></td><td></td></slu-6<>	6Z, K6.1 specifications>		
	ZA, ZB, ZC-axis <steady rest=""></steady>	mm (in.		4,870 (191.7) <2>	4,310 (169.7) <3>		
	Max. spindle speed	min-	1,5	500	1,0	000	
	Number of spindle speed ranges			2 (winding char	nge-over speed)		
	Type of spindle nose		JIS	A ₂ -15	JIS /	A ₁ -20	
Spindle 1	Through-spindle hole diameter	mm (in.	185	(7.3)	275	(10.8)	
Opinuio 1	Min. spindle indexing increment			0.00	001°		
	Spindle bearing inner diameter	mm (in.	260	(10.2)	360	(14.2)	
	Spindle torque	Low speed N·m (ft·lbf	3,254/2,386 (2,400.0/	1,759.8) <25%ED/cont>	6,784/5,574 (5,003.6/	4,111.2) <30 min/cont>	
	opinale torque	High speed N·m (ft-lbf	1,447/1,061 (1,067.2/	782.6) <25%ED/cont>	3,016/2,481 (2,224.5/1	1,830.0) <30 min/cont>	
	Max. spindle speed	min:	-	1,500	-	1,000	
	Number of spindle speed ranges		_	2 (winding change-over speed)	-	2 (winding change-over speed)	
	Type of spindle nose		_	JIS A ₂ -15	-	JIS A ₁ -20	
	Through-spindle hole diameter	mm (in.	_	185 (7.3)	_	275 (10.8)	
Spindle 2	Min. spindle indexing increment		_	0.0001°	_	0.0001°	
Opinidio 2	Spindle bearing inner diameter	mm (in.	_	260 (10.2)	_	360 (14.2)	
		Low speed N·m (ft-lbf)	_	3,254/2,386 (2,400.0/1,759.8) <25%ED/cont>	_	6,784/5,574 (5,003.6/4,111.2) <30 min/cont>	
	Spindle torque	High speed N·m (ft-lbf)	-	1,447/1,061 (1,067.2/782.6) <25%ED/cont>	-	3,016/2,481 (2,224.5/1,830.0) <30 min/cont>	
	Number of tool stations				1	200 11111/100110	
	B-axis indexing time				55]/90°		
	Min. B-axis indexing increment			1° [0.0			
	Max. tool spindle speed	min			000		
	Taper hole of rotary tool spindle			· · · · · · · · · · · · · · · · · · ·	Г50] [HSK-A100 (Т100)]		
	Type of retention knob		IDMG MOBI SEIKI 90	0°, Center through <mas dmg="" mori<="" td=""><td></td><td> KL90°> (BT50 only)]</td></mas>		KL90°> (BT50 only)]	
	Inner diameter of rotary tool spin	dle bearing mm (in.	<u> </u>	100			
Tool spindle	Tool storage capacity	(50 [100,	 		
		With adjacent tools mm (in.			(φ 4.7)		
	Max. tool diameter	Without adjacent tools mm (in.)			(φ 9.8)	-	
	Max. tool length	mm (in.		600 (
	Max. tool mass	kg (lb.)		30	· · · · · · · · · · · · · · · · · · ·		
				29.4	· · ·		
	Max. tool mass moment < from s	oindle gauge line> N·m (ft·lbf	(A tool with a mass moment greater t	han the maximum tool mass moment m		ns even if it satisfies other conditions.)	
	Spindle torque <15%ED/15 min/	cont> N·m (ft·lbf		302/175/147 (22	22.7/129.1/108.4)		
	Tailstock spindle diameter	mm (in.	150 (5.9) [180 (7.1)]		150 (5.9) [180 (7.1)]	-	
Tailstock	Taper hole of tailstock spindle		MT5 [MT6] <built-in></built-in>	=	MT5 [MT6] <built-in></built-in>	-	
	Tailstock spindle travel	mm (in.		-	150 (5.9)	-	
Feedrate	Rapid traverse rate	m/min (fpm), Z: 32 (105.0) Spindle 2 A: 15 (49.2) B: 23.8 [80 < Full indexing	. , , ,	XB, XC: 1.6 (5.2) ZA, ZB, ZC: 8 (26.2)	
	Spindle 1 drive motor	kW (HP) <25%ED/30 min/cont>	-	<30 min/cont>	
Motors	Spindle 2 drive motor	kW (HP	_	30/26/22 (40/34.7/30) <25%ED/30 min/cont>	-	45/37 (60/50) <30 min/cont>	
	Tool spindle drive motor <30 min	/cont> kW (HP)		30/22	(40/30)		
	Coolant pump motor <60/50Hz>) <0.73 (0.97)>×1 1.040 (1.39) <	· · · · · · · · · · · · · · · · · · ·	5 (1.0)>×1	
Power sources	Electrical power supply <cont></cont>	kVA	,	96.6	84.5	131.4	
(Standard)	Compressed air supply	MPa (psi), L/min (gpm)		0.5 (72.5), 900			
Tank capacity	Coolant tank capacity	L (gal.			(396.0)		
	Machine height <from floor=""></from>	mm (in.		e type: 4,281 (168.5)] [Hinge type+		69.9)]	
Machine size	Floor space <width×depth></width×depth>	mm (in.			×4,629 (182.2)	· · · · · · · ·	
	Mass of machine	kg (lb.)		55,000 (121,000)	53,500 (117,700)	56,000 (123,200)	
Noise data	A-weighted, time-average radiate			56—79 (measurement		00,000 (120,200)	
[] Ontion		uL				NT6600 DCG (130617)	

] Option

NT6600 DCG (130617)

- For the specifications of C-type, please contact DMG MORI SEIKI.
- *2 When selecting the two-face contact tool specification, be sure to use a two-face contact tool.

 Bar work capacity: Depending on the chuck/cylinder used and its restrictions, it may not be possible to reach full bar work capacity.

- Max. spindle speed: Depending on restrictions imposed by the workpiece clamping device, fixture and tool used, it may not be possible to rotate at the maximum spindle speed.

 ANR: ANR refers to a standard atmospheric state; i.e., temperature at 20°C (68°F); absolute pressure at 101.3 kPa (14.7 psi); and relative humidity at 65%.

 Power sources, machine size: the actual values may differ from those specified in the catalogue, depending on the optional features and peripheral equipment.

 Compressed air supply: Please be sure to supply clean compressed air repressure: 0.7 MPa (101.5 psi), pressure dew point: 10°C (50°F) or belows.

 A criterion capacity to select a compressor is 90 L/min (23.8 gpm) per 0.75 kW (1 HP). However, this figure may differ depending on the type of compressors and options attached. For details, please check the compressor specifications.
- When the tool tip air blow is regularly used, air supply of more than 300 L/min (79.2 gpm) is separately required.
 Noise data: the measurement was performed at the front of the NT6600 DCG/6000s machine with a maximum spindle speed of 1,400 min⁻¹. For details, please consult with our sales representative.
- The information in this catalog is valid as of June 2013.



2-year warranty, twice the peace of mind.

For machines delivered outside of Japan, parts relating to machine breakdown will be guaranteed free for 2 years from the date of installation, and labor costs to repair will be free for 1 year. Please contact our sales representative for details.



<Pre><Pre>cautions for Machine Relocation>

EXPORTATION: All contracts are subject to export permit by the Government of Japan. Customer shall comply with the laws and regulations of the exporting country governing the exportation or re-exportation of the Equipment, including but not limited to the Export Administration Regulations. The Equipment is subject to export restrictions imposed by Japan and other exporting countries and the Customer will not export or permit the export of the Equipment anywhere outside the exporting country without proper government authorization. To prevent the illegal diversion of the Equipment to individuals or nations that threaten international security, it may include a "Relocation Machine Security Function" that automatically disables the Equipment if it is moved following installation. If the Equipment is so-disabled, it can only be re-enabled by contacting DMG MORI SEIKI or its distributor representative. DMG MORI SEIKI and its distributor representative may refuse to re-enable the Equipment if it determines that doing so would be an unauthorized export of technology or otherwise violates applicable export restrictions. DMG MORI SEIKI and its distributor representative shall have no obligation to re-enable such Equipment. DMG MORI SEIKI and its distributor representative shall have no liability (including for lost profits or business interruption or under the limited service warranty included herein) as a result of the Equipment being disabled.

- DCG, DDM, BMT and ORC are trademarks or registered trademarks of DMG MORI SEIKI CO., LTD. in Japan, the USA and other countries
- If you have any questions regarding the content, contact our sales representative.
- The information in this catalog is valid as of October 2013. Designs and specifications are subject to changes without notice.

 The machines shown in the catalog may differ from the actual machines. The location and the size of the nameplates may also differ from the actual machines, or the nameplates may not be attached to some machines.
- DMG MORI SEIKI is not responsible for differences between the information in the catalog and the actual machine.

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